



## Detection of Diabetic Retinopathy Using Convolutional Neural Network

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# Detection of Diabetic retinopathy using Convolutional Neural Network

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**ABSTRACT:** *Images of the retina taken by a fundus camera are used to diagnose diabetic retinopathy which requires experienced optometrist to recognize the level of severity and significant features to reduce the time consumption and difficulty using complex grading. We suggest a convolutional neural network architecture in this paper to diagnose the diabetic retinopathy and accurately classify its severity by data augmentation which can recognize the characteristics like micro-aneurysm, hard exudates and haemorrhages. We train the data which is available on kaggle. We have a data set of 2755 images which is used in our proposed method to achieve an accuracy of 91.67% .*

**KEYWORDS:** *convolutional neural networks, Image classification, Diabetic retinopathy, deep learning.*

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A disease of the retina known as diabetic retinopathy which can cause blurry vision and complete blindness. DR is a condition which can not be cured but treated at early stages. DR occurs with time and affects blood vessels in the retina. Due to increasing life-expectancy, modern lifestyle people become more prone to be diabetic. The diabetic person should get them tested once in a year which is costly. This is the reason behind proposing the CNN model through which DR patients do not need to visit the clinics.

The reason behind recognizing the severity of DR as soon as possible is that it can not be cured. The classification of the numerous characteristics is a bit of a time taking process for technicians. Computers are able to achieve the classification of features much quickly.

Kth nearest neighbour classifiers and Support vector machine is being used extensively to identify the characteristics and determine the stage of DR. Most learning techniques for classification are two-class classifications for DR or no DR.

## 1. INTRODUCTION

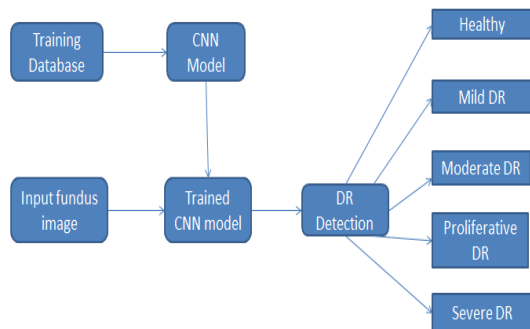
We propose a project in which there is a website for detecting DR. This website has the interface having a login page. After login, a user can choose a file or image of the fundus image. CNN is used as an algorithm for classifying the fundus images. A subset of deep learning known as convolutional neural networks (CNNs) has a notable track record for use in the medical stream for imaging. All the information about a user is collected as a database. MongoDB and NodeJS are used for back-end and front-end.

There are two main aims of achieving a desirable sensitivity and accuracy. This significantly classifies the problem into five classes which are

1. healthy
2. mild DR
3. moderate DR
4. proliferative DR
5. severe DR.

Overfitting is also another concern for neural networks. Massive skewness is common in large datasets.

The evaluation of the model is done by confusion matrix and F\_score. This model can classify the input image of retina into five classes. ANN can also be used for classification but accuracy came out lesser than CNN.

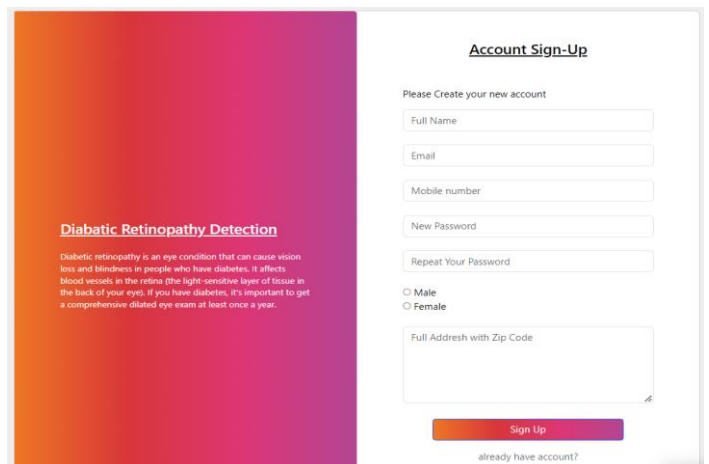
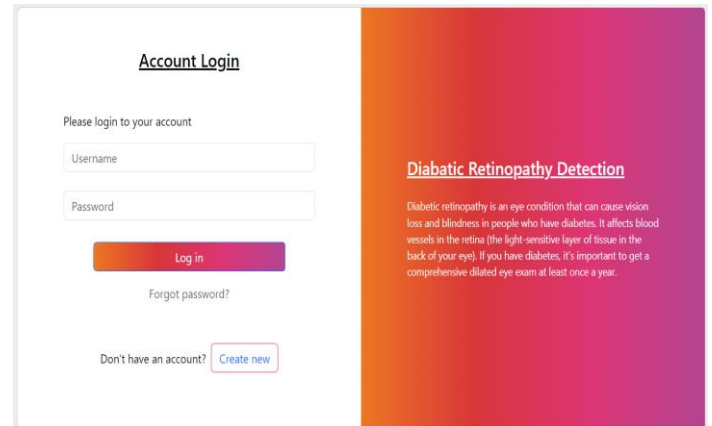


System Architecture

## 2. METHODOLOGY:

In this project, a user interface is provided to login and signup for those who already have an account. Pug template is used for front-end, Node.js and Express.js for backend and MongoDB is used for creating databases. Then merged the

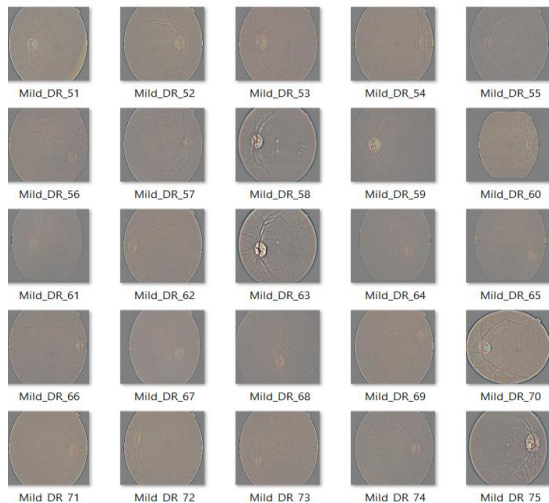
machine learning code and web development code using Node.js including Tensorflow.js.



1. DATASET AND SOFTWARE: The dataset can be obtained from kaggle which is present all the time. Dataset is divided in five labels:

1. Healthy( 1000 images of size 256 \* 256).
2. Mild DR( 370 images of size 256 \* 256).
3. Moderate DR( 900 images of size 256 \* 256).
4. Proliferative DR( 290 images of size 256 \* 256).
5. Severe DR( 190 images of size 256 \* 256)

Keras is used with Tensorflow(<https://www.tensorflow.org/install/pip>) as back end. These two were picked because of their thorough documentation and speedy computation. The classification of an image takes about 0.04 seconds, making it possible to provide the patient with feedback in real time.



**2. DATA EVALUATION:** In this step, we are getting all the files by importing 'os'. Then data is being evaluated by checking out the first five rows, finding the length, and doing some value counts.

**3. DATA PRE-PROCESSING:** The collection included pictures of patients in a range of age groups and lighting conditions. To normalise the size of each image and colour. The size of dataset of 2750 images are converted into an array of size 75\*75\*3. By importing labelEncoder from sklearn we are getting the first five labels and then fit the model by using fit\_transform. Then splitting of data is done by splitting train and test into 70% and 30% respectively.

```

for f in file:
    img = cv2.imread(data_path+'/'+f)
    img = cv2.resize(img,(image_size,image_size))
    images.append(img)
    labels.append(1)

In [8]: # Transform the image array to a numpy type
images = np.array(images)
images.shape
Out[8]: (2750, 150, 150, 3)

In [9]: images = images.astype('int64')/255.0

In [10]: images.shape
Out[10]: (2750, 150, 150, 3)

In [11]: from sklearn.preprocessing import LabelEncoder,OneHotEncoder
y = fundus_df['dr_stage'].values
print(y[:5])
['Healthy' 'Healthy' 'Healthy' 'Healthy' 'Healthy']

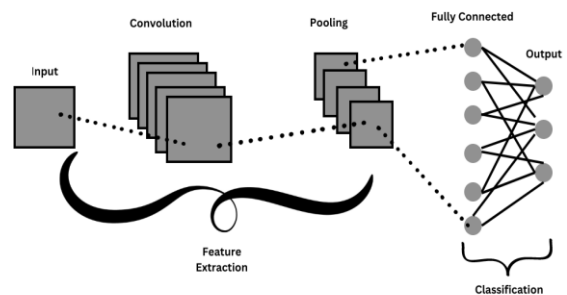
In [12]: # for y
y_labelencoder = LabelEncoder()
y = y_labelencoder.fit_transform(y)
print(y)
[0 0 0 ... 4 4 4]

```

#### 4. CONVOLUTIONAL NEURAL NETWORK:

The network architecture known as a CNN is specifically utilised for picture classification and recognition. CNNs use different types of multi perceptrons layers to minimise preprocessing..

Convolutional networks' fundamental concept is derived from biological processes; it is comparable to the neuron network in the animal brain's visual cortex. Receptive field, a specific region of the visual field, is where single neurons respond. In the end, every single neuron's receptive field integrates to cover the entire visual field. Comparing CNN's preprocessing to other classification methods, it is quite minimal.. In contrast to traditional algorithms, which learn manually, the network learns the filters automatically. Convolutional layer, ReLu (Introducing NonLinearity) layer employing arctan or sigmoid function, Pooling layer, and fully linked layer make up the majority of its layers.

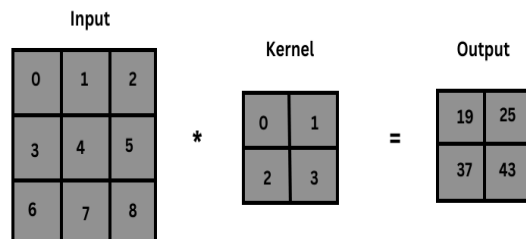


CNN Architecture

#### 1.Convolutional Layer:

The main job of a CNN is to extricate characteristics from an image given by the user. It keeps the link between pixels while learning visual attributes using a tiny matrix known as strides of data given by user. The filter is moved over the input image to create a feature map. In contrast to filters, feature maps are provided separately for each input image.

We are using Conv2D having filters of 32 , size of 5\*5 ,activation of 'relu'and input size of 75\*75\*3(same as array size).



Filter Matrix

#### 2.Max Pooling Layer:

Max pooling process is mainly used to minimise the size of the image for retaining the most important features. Sub-sampling and down-sampling are other names for it. Max, Average, Sum, and more types of pooling are available. The feature matrix's elements are replaced by their averages in average downsampling. The feature matrix's elements are replaced by the maximum among them while using max down sampling. The elements of the feature matrix are replaced by the sum of the elements in sum down sampling. Max pooling typically produces the greatest results among the aforementioned pooling approaches in CNN, according to practical experience. It lessens the number of network parameters and calculations, which controls overfitting while also making the input depiction (feature dimension) smaller and easier to manage.

### 3. Fully Connected Layer:

It's primary duty is to classify the input image using the training dataset and these attributes. All of the output goals from this layer should total up to 1 when added together. The probabilistic classifier Softmax serves as the sigmoid function for the output layer. A vector of randomly generated real-value scores is compressed by the softmax function to a value between zero and one that adds up to 1.

This is done 3 times with different filters and only in the first layer we have to mention the input size. Densifying is done by flattening and densifying using activation softmax function.

```
In [4]:
cnf = keras.Sequential([
    layers.Conv2D(filters=32, kernel_size=(5,5), activation = 'relu', input_shape=(150,150)),
    layers.MaxPooling2D((2,2)),

    layers.Conv2D(filters=64, kernel_size=(5,5), activation = 'relu'),
    layers.MaxPooling2D((2,2)),

    layers.Conv2D(filters=128, kernel_size=(5,5), activation = 'relu'),
    layers.MaxPooling2D((2,2)),

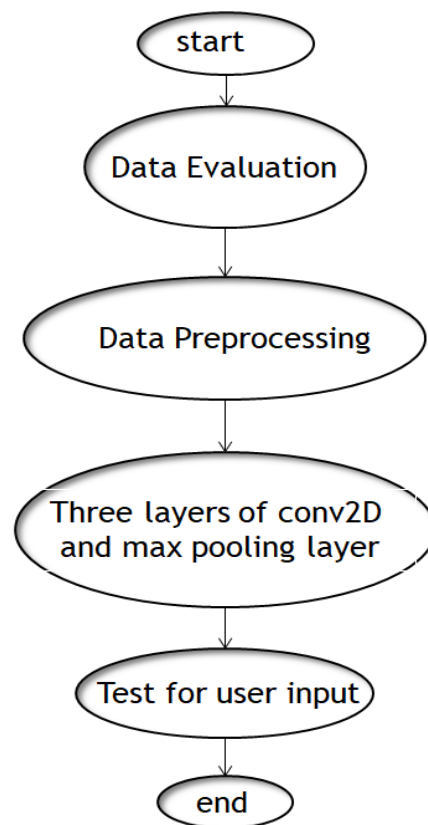
    #dense

    layers.Flatten(),
    layers.Dense(128, activation = 'relu'),
    layers.Dense(10, activation = 'softmax')
])
```

**5. EVALUATION AND TESTING:** We are fitting the cnn model with epochs equal to 50 to increase the accuracy.

```
Epoch 41/50
83/83 [=====] - 25s 296ms/step - loss: 0.4237 - accuracy: 0.8439
Epoch 42/50
83/83 [=====] - 25s 301ms/step - loss: 0.3931 - accuracy: 0.8580
Epoch 43/50
83/83 [=====] - 27s 321ms/step - loss: 0.3796 - accuracy: 0.8606
Epoch 44/50
83/83 [=====] - 25s 296ms/step - loss: 0.3561 - accuracy: 0.8716
Epoch 45/50
83/83 [=====] - 25s 298ms/step - loss: 0.3314 - accuracy: 0.8769
Epoch 46/50
83/83 [=====] - 25s 296ms/step - loss: 0.3321 - accuracy: 0.8788
Epoch 47/50
83/83 [=====] - 25s 298ms/step - loss: 0.2924 - accuracy: 0.9000
Epoch 48/50
83/83 [=====] - 25s 298ms/step - loss: 0.3138 - accuracy: 0.8894
Epoch 49/50
83/83 [=====] - 25s 299ms/step - loss: 0.2757 - accuracy: 0.9098
Epoch 50/50
83/83 [=====] - 25s 302ms/step - loss: 0.2557 - accuracy: 0.9167

<tensorflow.python.keras.callbacks.History at 0x268ab27b7c0>
```



Flowchart of implementation

### 3. RESULTS:

The dataset has 2755 photos utilised for validation. According to the five-class problem, the accuracy is calculated by dividing the total number of true

positive and true negative results by the total number of true positive, true negative, true positive, and false positive results

The accurate classification of patients is how we determine accuracy. The trained network obtained 30% sensitivity and 91.67% accuracy. The network's classifications were denoted by the numbers 0 -healthy, 1 -mild DR, 2 -moderate DR, 3 -proliferative DR, and 4 -severe DR.

$$\text{Accuracy} = \frac{\text{TP} + \text{TN}}{\text{TP} + \text{TN} + \text{FN} + \text{FP}}$$

#### 4.COMPARATIVE ANALYSIS:

Name	Technique	Result	Type
Ratul Ghosh ,et. al.[1]	CNN using theano	85	DR/N O DR
Ratul Ghosh ,et. al.[1]	CNN using theano	95	5 CLAS S
Xiaoliang Wang,et. al[2]	InceptionNet V3	63.23	5 CLAS S
Yu Shang, et. al,[3]	CNN	91	DR/N O DR
Kwasigroch, et. al.[4]	CNN	51	5 CLAS S
Kwasigroch, et. al.[4]	CNN	81	DR/N O DR
Li Xiaogang, et. al.[5]	CNN	92	DR/N O DR

Enrique Carrera,et. al.[9]	SVM	85	DR/N O DR
Arisha Roy, et. al.[10]	SVM	96.23	DR/N O DR
Ours	CNN	91.67	5 CLAS S

#### 5.FUTURE SCOPE:

1. Making a CNN model using image processing for extricating the attributes of the retina image. The resizing of the fundus images in the same dimensions as input to the CNN.Three layers of conv2D used to decrease the time and increase the accuracy.
2. Creating an interactive front end graphical user interface for the model using the free source Python package FLASK in order to improve human engagement for model deployment.
3. Raising the dimensions of the training data set and employing powerful GPUs to implement the model will increase accuracy.

#### 6.CONCLUSION:

Using colour fundus pictures, a model is proposed for classifying DR stages according to severity. The effectiveness of CNN model is being evaluated using various indicators. The performance of the suggested model is satisfactory, accuracy comes out to be 91.67 percent for five class classification on the Kaggle dataset. The model retains the ability to be implemented as a user-interactive programme that can shorten the time needed for diagnosis from two weeks to one day.

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## Field Optical Coherence Tomography

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